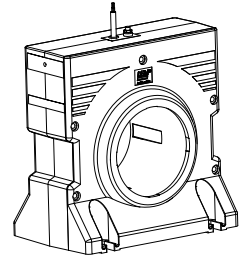


# Current Transducer RA 2000-S/SP1

For the measurement of alternating components in a determined bandwidth, contained in a continuous primary current.



## Electrical data

$M$	Mutual inductance		$4.4018 \cdot 10^{-6}$	H
$U_{out}$	Output voltage (analog)	$U_{out} =$	$M \cdot \frac{di_p}{dt}$	V
	When $I_p$ has a sinusoidal shape	$U_{out\ RMS} =$	$2 \cdot \pi \cdot M \cdot f \cdot I_{p\ RMS}$	V
			$2 \cdot \pi \cdot M = 27.657 \cdot 10^{-6}$	H
Examples:		$U_{out\ RMS} = 4.4018 \cdot 10^{-6} \cdot 2 \cdot \pi \cdot 50 \cdot 50 = 0.069$		@ 50 Hz, 50 A
		$U_{out\ RMS} = 4.4018 \cdot 10^{-6} \cdot 2 \cdot \pi \cdot 3000 \cdot 50 = 4.140$		@ 3000 Hz, 50 A
$L_S$	Inductance of secondary circuit ( $\pm 6\%$ )		8.65	mH
$N_S$	Number of secondary turns		1920	

## Accuracy - Dynamic performance data

$BW$	Frequency bandwidth		20 ... 3000	Hz
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## Test circuit

$L_T$	Inductance of test circuit ( $\pm 6\%$ )		8.75	mH
$N_T$	Number of turns (test winding)		1920	
$R_T$	Resistance of test winding @ $T_A = 70^\circ\text{C}$ ( $\pm 3\%$ )		134	$\Omega$
$I_T$	Test current		< 50	mA

## General data

$T_A$	Ambient operating temperature		-25 ... 70	$^\circ\text{C}$
$T_S$	Ambient storage temperature		-40 ... 85	$^\circ\text{C}$
$T_B$	Primary conductor temperature		$\leq 100$	$^\circ\text{C}$
$R_S$	Secondary coil resistance @ $T_A = 70^\circ\text{C}$ ( $\pm 3\%$ )		131	$\Omega$
$m$	Mass		6	kg
	Standards		EN 50155: 2007	
			EN 50121-3-2: 2015	

## Feature

- Insulating plastic case recognized according to UL 94-V0.

## Special features

- Shielded cable: 2 m
- Connection to screen: M5

## Advantages

- No insertion losses
- Current overload capability.

## Applications

- Single or three phase inverters
- Propulsion and braking chopper
- Propulsion converter.

## Application Domain

- Traction.

## Current Transducer RA 2000-S/SP1

### Accuracy

Accuracy for the measurement of a single frequency signal:

Amplitude error: in % of the measured signal.

Frequency Amplitude	20 Hz ... 100 Hz		10 Hz ... 3000 Hz	
	Amplitude error	Phase error in °	Amplitude error	Phase error in °
0.1 A ... 1 A	±2.8	-90 ±5	±2.7	-90 ±2.5
1 ... 10 A	±2.5	-90 ±5	±2.6	-90 ±2.5
10 ... 20 A	±2.9	-90 ±5	±3.0	-90 ±2.5

Table 1.1 - Maximum amplitude and phase errors for single frequency signals.

### Accuracy for the measurement of signal added to a DC current of > 10 A

Amplitude error: in % of the measured signal.

Frequency Amplitude	20 Hz ... 100 Hz		10 Hz ... 3000 Hz	
	Amplitude error	Phase error in °	Amplitude error	Phase error in °
0.1 A ... 1 A	±2.8	-90 ±5	±2.7	-90 ±2.5
1 ... 10 A	±2.5	-90 ±5	±2.6	-90 ±2.5
10 ... 20 A	±2.9	-90 ±5	±3.0	-90 ±2.5

Table 1.2 - Maximum amplitude and phase errors for signals added to a minimum DC fundamental.

The values are the same as without DC (see 1.1)

### Accuracy for the measurement of signal added to a AC (fundamental) current in the range between 15 Hz and 100 Hz of > 10 A RMS

Amplitude error: in % of the measured signal.

Frequency Amplitude	20 Hz ... 100 Hz		10 Hz ... 3000 Hz	
	Amplitude error	Phase error in °	Amplitude error	Phase error in °
0.1 A ... 1 A	±2.8	-90 ±5	±2.7	-90 ±2.5
1 ... 10 A	±2.5	-90 ±5	±2.6	-90 ±2.5
10 ... 20 A	±2.9	-90 ±5	±3.0	-90 ±2.5

Table 1.3 - Maximum amplitude and phase errors for signal added to a minimum AC fundamental.

## Current Transducer RA 2000-S/SP1

### Insulation coordination

$U_d$	RMS voltage for AC insulation test, 50 Hz, 1 min	12 <sup>1)</sup>	kV
		500 <sup>2)</sup>	V
		Min	
$d_{cp}$	Creepage distance	113.5	mm
$d_{ci}$	Clearance	107.8	mm
$CTI$	Comparative Tracking Index (group I)	600	

**Notes:** <sup>1)</sup> Between primary and secondary + test winding

<sup>2)</sup> Between secondary and test winding.

## Safety



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary busbar, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used.

Main supply must be able to be disconnected.

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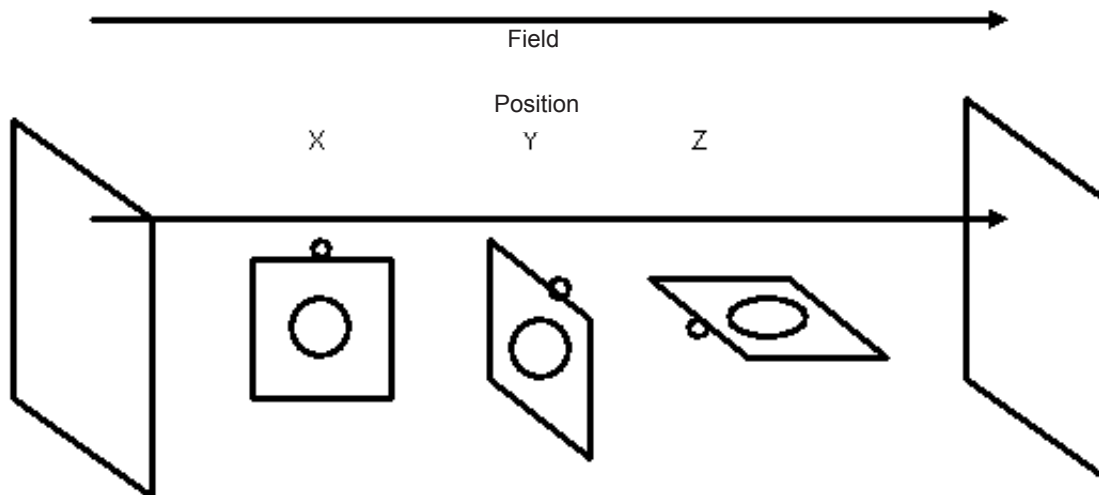
### Influence of external magnetic fields

Table 2-1 shows the error in the measurement of the primary current (mA RMS) due to external magnetic fields at the frequency of the external field. The errors are measured with respect to the theoretically expected signal. The influence is different for the 3 axes of the transducer. See Figure 2-1 for the orientation of the axes.

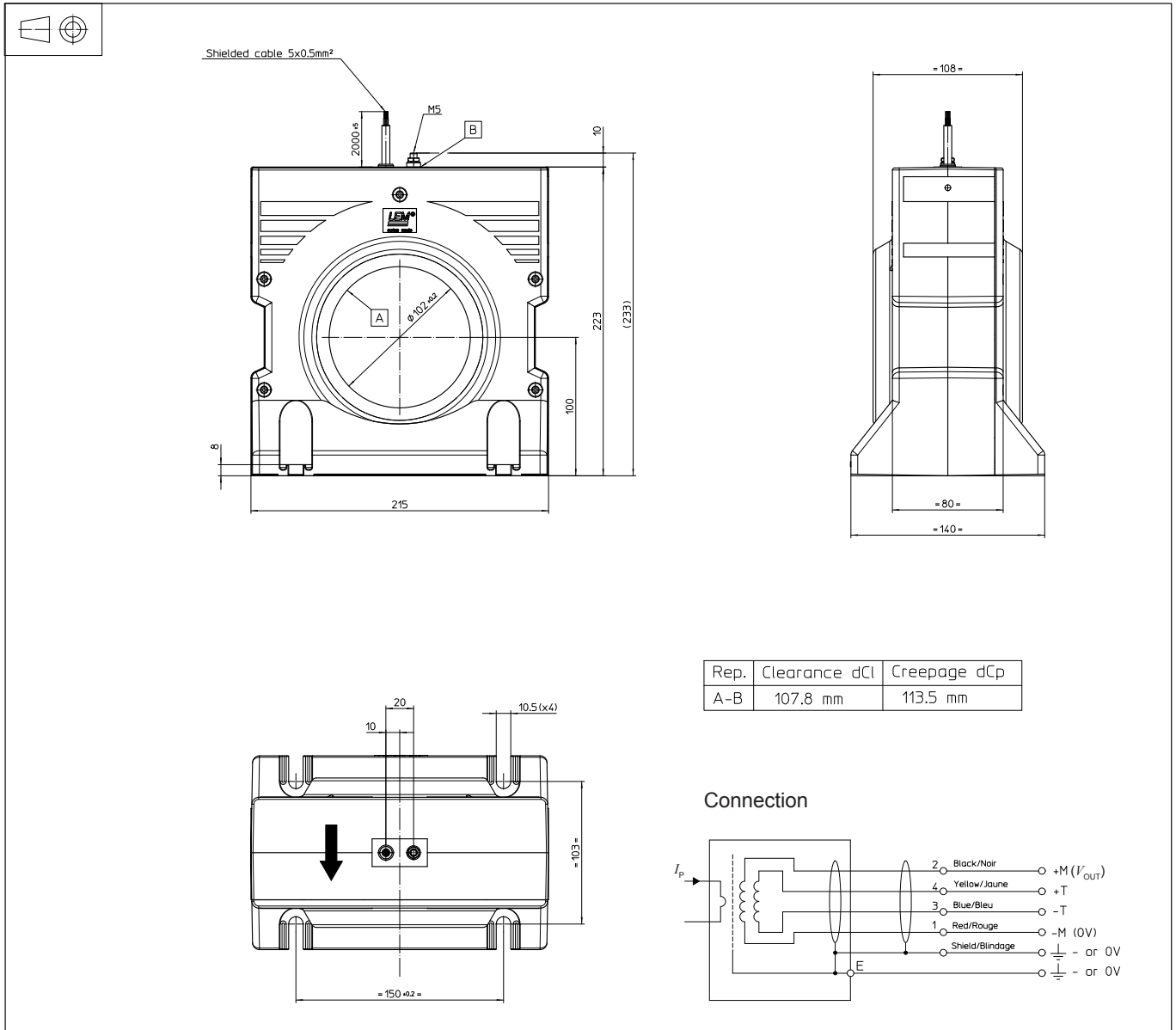
At 50 Hz:

Position \ Frequency	X	Y	Z
	mAT/A/m	mAT/A/m	mAT/A/m
$H_{AC}$ @ 50 Hz	5	18.2	1.54
$H_{AC}$ @ 300 Hz	17.6	49.2	1.96

Table 2.1 - Influence of external magnetic fields in each axes of the transducer.



## Dimensions RA 2000-S/SP1 (in mm)



### Mechanical characteristics

- General tolerance ±1 mm
- Transducer fastening 4 slots ∅ 10.5 mm  
4 steel screws M10  
Recommended fastening torque 11.5 N·m
- Primary through-hole ∅ 102 mm
- Connection of secondary shielded cable 5 x 0.5 mm<sup>2</sup>
- Connection of screen M5 threaded stud  
Recommended fastening torque 2.2 N·m

### Remarks

- $U_s$  is positive when  $di/dt$  flows in the direction of the arrow.
- Temperature of the primary conductor should not exceed 100 °C.